8790-01

PAS

GENERAL INFORMATION

1. SPECIFICATIONS FOR PAS

Item	Item	Specification
	Rated voltage	DC 13.6 V (IGN power)
	Operating voltage	DC 9.0 V ~ 16.0 V
	Operating temperature	-30℃ ~ +80℃
PAS unit	Maximum humidity	95%
	High internal pressure	24 V
	Insulation resistance	No heat & fire due to current leak
	Max. permissible current	Unit: 100 mA or less Sensor: 35 mA or less
	Operating frequency	58 KHz
PAS sensor	Detection range	30 cm~120 cm (based on lineal distance between sensor and obstacle)
	Tolerance	± 10 cm
	Operating voltage range	DC 8 V

2. CAUTIONS

- Note that the display does not show everything in the rear area. Always check nobody, especially animals and children, is behind the vehicle when parking or reversing.
- If you can not properly check the vehicle behind, get out of the vehicle and then visually check it.
- 1. The parking aid system is just a supplemental device to help your parking.
- 2. Always keep the safety precautions.
- Do not press or shock the sensors by hitting or using a high-pressure water gun while washing, since it may damage the sensors.
- 4. If the system is in normal operating condition, a short beep sounds when the shift lever is moved into "R" position with the ignition key "ON".
- 5. If the system is defective, the warning buzzer sounds for 3 seconds when moving the gear shift lever to "R" position with the ignition ON. Be careful not to confuse this and the parking aid alarm (in 50 cm).
- ▶ The parking aid system will not work or improperly work under following cases:

1) Certain obstacles that sensors can not detect

- Thin and narrow objects, such as wires, ropes, chains
- Cotton, sponge, clothes, snow; that absorb ultrasonic waves
- Obstacles lower than the bumper (ex. drain ditch or mud puddle)

2) Not defective but improperly working

- When the sensing portion is frozen (operates normally after thawed)
- When the sensing portion is covered by rain, water drops, snow or mud (operates normally after cleaned)
- When receiving other ultrasonic signals (metal sound or air braking noises from heavy commercial vehicles)
- When a high-power radio is turned on

3) Narrowed sensing area

- When the sensing portion is partially covered by snow or mud (operates normally after cleaned)
- Surrounding temperature of sensor is too high (approx. over 80°C) or too low (approx. below −30°C)

4) Not defective but may cause malfunction

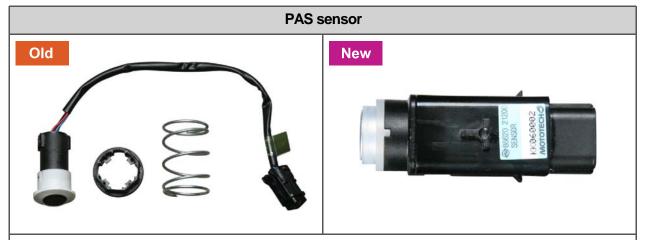
- When driving on the rough roads, gravel road, hill and grass
- When the bumper height is changed due to heavy load
- When the sensing portion is frozen
- When the sensing portion is covered by rain, water drops, snow or mud
- When receiving other ultrasonic signals (metal sound or air braking noises from heavy commercial vehicles)
- When a high-power radio is turned on
- When some accessories are attached in detecting ranges

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Modification basis	
Application basis	
Affected VIN	

3. Major changes for PAS unit



Operating frequency changed (40 KHz \rightarrow 58 KHz) and sensor appearance and connector changed (insert type)



Modification basis Application basis Affected VIN

OVERVIEW AND OPERATING PROCESS

1. Overview

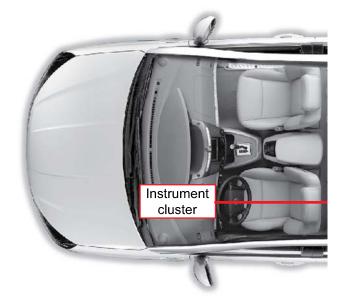
The parking aid system (PAS) is a supplementary device which detects the distance to any obstacle with the ultrasonic sensors equipped to the rear bumper and warns the driver with alarm sounds, when the vehicle is moving backward.

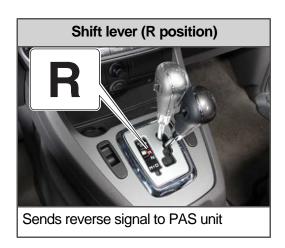
The system emits the ultrasonic wave signals from the sensors on the rear bumper with a specific interval and detects the reflected signals from obstacles.

The alarm interval becomes shorter as the obstacle approaches to assure the safety distance and to facilitate parking of the vehicle.

2. Layout



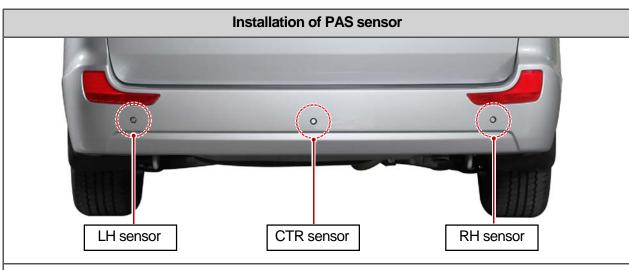




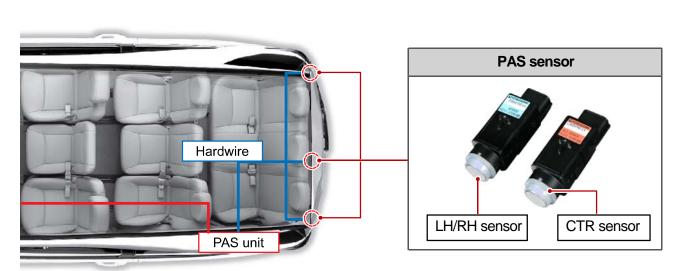
PAS

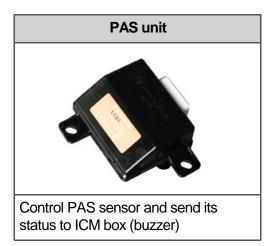
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Modification basis	
Application basis	
Affected VIN	



- Rear obstacle detection sensor : 3 off
- Activated for reverse driving only





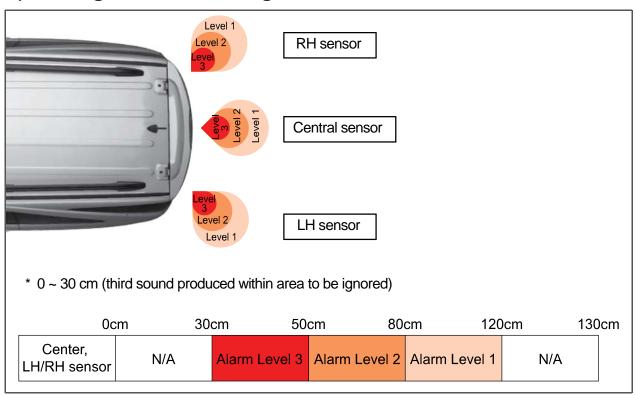
Modification basis	
Application basis	
Affected VIN	

3. Operation process

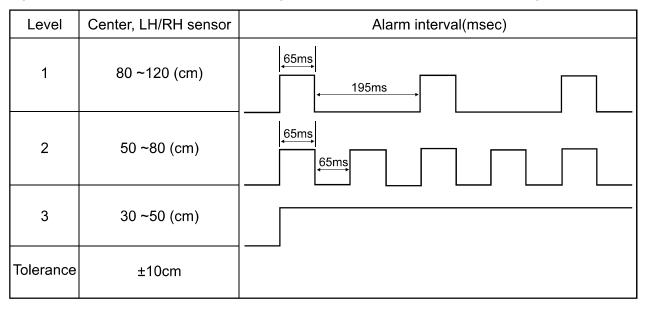
1) How to operate

- The PAS sensors are activated when the transmission gear is in the "R" (reverse) position.

2) Sensing distance and range



3) Alarm section and interval (from PAS buzzer in ICM box)



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Modification basis	
Application basis	
Affected VIN	

4) Detection range by sensors

30cm	Step 3	Step 2 50 ~ 80cm	Step 1 80 ~ 120cm	I I
Not detected				
Not detected				
		Impossible to detect		15cm

Height	Ground ~ 15 cm	15 cm ~ lower side of bumper	Lower side of bumper ~
Possible to detect	Impossible to detect	Not detected	Detected
Tolerance	± 5 cm	± 5 cm	± 5 cm

5) Distance calibration by temperature from temperature sensor

The ultrasonic wave sensor directs the distance value by receiving the sensor operating temperature from the sensor and compensating for the detecting deviation since it varies depending on the ambient temperature.

Temperature	Thermistor output value	Temperature	Thermistor output value
+80℃	6.93 V	+20℃	2.16 V
+70℃	6.24 V	+10℃	1.45 V
+60℃	6.04 V	0℃	1.15 V
+50℃	5.34 V	-10℃	0.98 V
+40℃	4.62 V	-20°C	0.88 V
+30℃	4.15 V	-30℃	0.75 V

Modification basis	
Application basis	
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4. Self-diagnosis

▶ PAS self-diagnosis mode (outputs warning beep via exterior buzzer)

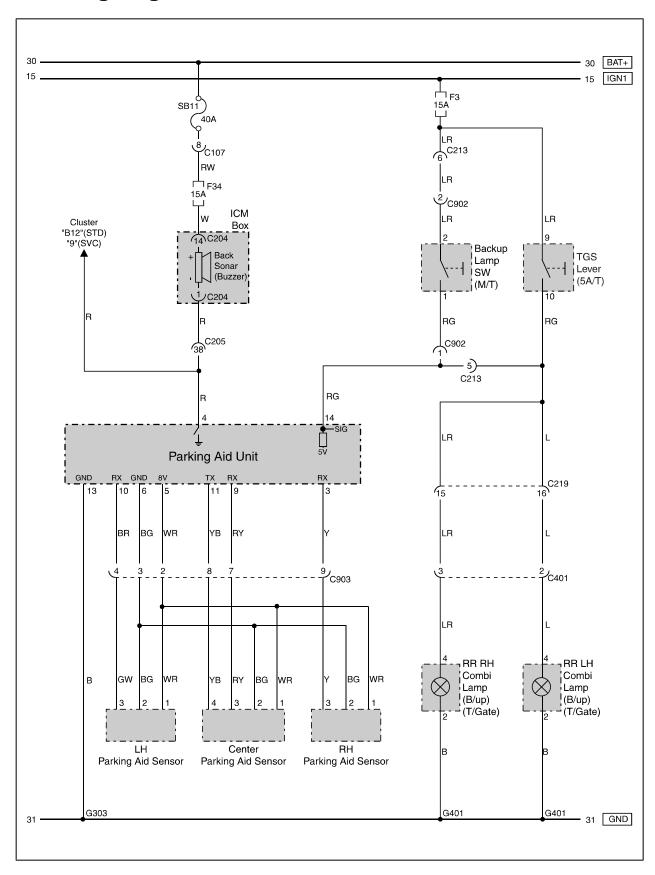
- System enters into this mode when gear shifted "R" position after initial ignition ON
- The self-diagnosis fails and the buzzer sounds under any of the following conditions:
 - a. Open circuit in sensor (TX)
 - b. Open circuit in power wires (+ and -)
 - c. In the event of sensor failure itself
- If normal, warning buzzer sounds for 0.065 seconds.

► Alarm interval during self-diagnosis

Defective	Alarm interval	Remark
Defective LH sensor	65ms 195ms 65ms	
Defective center sensor	65ms 65ms 65ms 65ms 65ms 65ms	
Defective RH sensor	65ms 65ms 65ms 65ms 65ms 65ms 65ms 65ms	
Defective two or more sensors	3000ms	

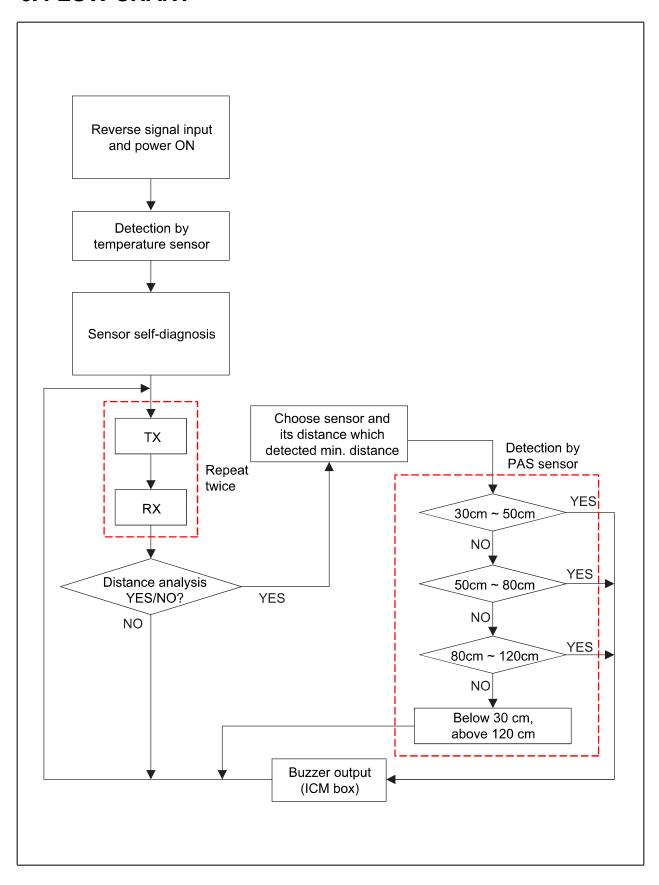
Modification basis	
Application basis	
Affected VIN	

5. Wiring diagram



Modification basis	
Application basis	
Affected VIN	

6. FLOW CHART



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Modification basis	
Application basis	
Affected VIN	